



Year 13 Pure Maths Curriculum Summary



– Y13 Pure Mathematics

| When? | Topic | Knowledge | Unit Assessments |
|-------------|----------------------|---|--|
| HALF TERM 1 | Algebraic methods | <ul style="list-style-type: none"> ● Use proof by contradiction to prove true statements ● Multiply and divide two or more algebraic fractions ● Add or subtract two or more algebraic fractions ● Convert an expression with linear factors in the denominator into partial fractions ● Convert an expression with repeated linear factors in the denominator into partial fractions ● Divide algebraic expressions ● Convert an improper fraction into partial fraction form | <ul style="list-style-type: none"> ● proof by contradiction ● add, subtract, times, divide algebraic fractions ● partial fractions with linear factors, repeated factors in denominator ● algebraic long division ● improper fractions |
| | Functions and graphs | <ul style="list-style-type: none"> ● Understand and use the modulus function ● Understand mappings and functions, and use domain and range ● combine two or more functions to make a composite function ● know how to find the inverse of a function graphically and algebraically ● Sketch the graphs of the modulus function $y = f(x)$ and $y = f(x)$ ● Apply a combination of two (or more) transformations to the same curve ● Transform the modulus function | <ul style="list-style-type: none"> ● modulus function ● mappings and functions ● domain and range ● composite function ● inverse of a function ● graphs of the modulus function $y = f(x)$ and $y = f(x)$ ● two (or more) transformations to the same curve |



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| | Sequences and series | <ul style="list-style-type: none"> ● Find the nth term of an arithmetic sequence ● Prove and use the formula for the sum of the first n terms of an arithmetic series ● Find the nth term of a geometric sequence ● Prove and use the formula for the sum of a finite geometric series ● Prove and use the formula for the sum to infinity of a convergent geometric series ● Use sigma notation to describe series ● Generate sequences from recurrence relations ● Model real-life situations with sequences and series | <ul style="list-style-type: none"> ● N-th term of an arithmetic and geometric ● S_n ● Sum to infinity ● sigma notation ● recurrence relations ● Model |
| HALF TERM 2 | Binomial expansion | <ul style="list-style-type: none"> ● Expand $(1 + x)^n$ for any rational constant n and determine the range of values of x for which the expression is valid ● Expand $(a + bx)^n$ for any rational constant n and determine the range of values of x for which the expression is valid ● Use partial fractions to expand fractional expressions | <ul style="list-style-type: none"> ● $(1 + x)^n$ ● $(a + bx)^n$ ● Use partial fractions |
| | Radians | <ul style="list-style-type: none"> ● Convert between degrees and radians and apply this to trigonometric graphs and their transformations ● Know exact values of angles measured in radians ● Find an arc length using radians ● Find areas of sectors and segments using radians ● Solve trigonometric equations in radians ● Use approximate trigonometric values when θ is small | <ul style="list-style-type: none"> ● Use radians, with trig graphs and their transformations ● Exact values eg $30 = \frac{\pi}{6}$ ● Arc length ● Sector area ● Solve trig equations with radians ● Trig approximations when θ is small |



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| | Trigonometric functions | <ul style="list-style-type: none"> • Understand the definition of secant, cosecant and cotangent and their relationship to cosine, sine and tangent • Understand the graphs of secant, cosecant and cotangent and their domain and range • Simplify expressions, prove simple identities and solve equations involving secant, cosecant and cotangent • Prove and use $\sec^2 x \equiv 1 + \tan^2 x$ and $\operatorname{cosec}^2 x \equiv 1 + \cot^2 x$ • understand and use inverse trigonometric functions and their domain and ranges | <ul style="list-style-type: none"> • Use sec, cosec, cot, and their graphs • Prove identities with sec, cosec, cot • Prove and use $\sec^2 x \equiv 1 + \tan^2 x$ and $\operatorname{cosec}^2 x \equiv 1 + \cot^2 x$ • inverse trigonometric functions and their domain and ranges |
| | Trigonometry and modelling | <ul style="list-style-type: none"> • Prove and use the addition formulae • understand and use the double-angle formulae • Solve trigonometric equations using the double-angle and addition formulae • Write expressions of the form $a \cos \theta \pm b \sin \theta$ in the form $R \cos(\theta \pm a)$ or $R \sin(\theta \pm a)$ • Prove trigonometric identities using a variety of identities • Use trigonometric functions to model real-life situations | <ul style="list-style-type: none"> • addition formulae • double-angle formulae • Solve trigonometric equations using the double-angle and addition formulae • $R \cos(\theta \pm a)$, $R \sin(\theta \pm a)$ • Prove trigonometric identities • Use trigonometric functions to model real-life situations |
| HALF TERM 3 | Parametric equations | <ul style="list-style-type: none"> • Convert parametric equations into Cartesian form by substitution • Convert parametric equations into Cartesian form using trigonometric identities • Understand and use parametric equations of curves and sketch parametric curves • Solve coordinate geometry problems involving parametric equations • Use parametric equations in modelling in a variety of contexts | <ul style="list-style-type: none"> • parametric equations into Cartesian • parametric equations into Cartesian form using trigonometric identities • use parametric equations of curves • sketch parametric curves • Solve coordinate geometry problems • modelling |



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| | Differentiation | <ul style="list-style-type: none"> • Differentiate trigonometric functions • Differentiate exponentials and logarithms • Differentiate functions using the chain, product and quotient rules • Differentiate parametric equations • Differentiate functions which are defined implicitly • Use the second derivative to describe the behaviour of a function • Solve problems involving connected rates of change and construct simple differential equations | Differentiation of/using <ul style="list-style-type: none"> • trigonometric functions • exponentials and logarithms • using the chain, product and quotient rules • parametric equations • implicit • second derivative connected rates of change differential equations |
| HALF TERM 4 | Numerical methods | <ul style="list-style-type: none"> • Locate roots of $f(x) = 0$ by considering changes of sign • Use iteration to find an approximation to the root of the equation $f(x) = 0$ • Use the Newton-Raphson procedure to find approximations of the solutions of equations in the form $f(x) = 0$ • Use numerical methods to solve problems in context | <ul style="list-style-type: none"> • Locate roots • Iteration • Newton Raphson • Numerical methods • |
| | Integration | <ul style="list-style-type: none"> • Integrate standard mathematical functions including trigonometric and exponential functions and use the reverse of the chain rule to integrate functions in the form of $f(ax + b)$ • Use trigonometric identities in integration • Use the reverse of the chain rule to integrate more complex functions • Integrate functions by making a substitution, using integration by parts and using partial fractions • Use integration to find the area under a curve • Use the trapezium rule to approximate the area under a curve • Solve simple differential equations and model real-life situations with differential equations | Integrate: <ul style="list-style-type: none"> • Trig functions • Exponentials • Using reverse chain rule • Using trig identities • By substitution • By parts • Using partial fractions • To find area under a curve Trapezium rule Solve differential equations, and model |



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| | Vectors | <ul style="list-style-type: none">• Understand 3D Cartesian coordinates• Use vectors in three dimensions• Use vectors to solve geometric problems• Model 3D motion in mechanics with vectors | <ul style="list-style-type: none">• 3D coordinates• Vectors in 3D• Solve problems with vectors• 3D motion |