



Year 12 Mechanics Curriculum Summary



Y12 Mechanics

When?	Topic	Knowledge	Unit Assessment
HALF TERM 1	Modelling in Mechanics	<ul style="list-style-type: none">• Understand how the concept of a mathematical model applies to mechanics• Understand and be able to apply some of the common assumptions used in mechanical models• Know SI units for quantities and derived quantities used in mechanics• Know the difference between scalar and vector quantities	<ul style="list-style-type: none">• Mathematical models• Mechanical models• Units of measure• Scalar and vector quantities
HALF TERM 3	Constant Acceleration	<ul style="list-style-type: none">• Understand and interpret displacement-time graphs• Understand and interpret velocity-time graphs• Derive the constant acceleration formulae and use them to solve problems• Use the constant acceleration formulae to solve problems involving vertical motion under gravity	<ul style="list-style-type: none">• Displacement-time graphs• Constant acceleration formulae• Solve problems involving vertical motion under gravity
HALF TERM 5	Forces & Motion	<ul style="list-style-type: none">• Draw force diagrams and calculate resultant forces• Understand and use Newton's first law• Calculate resultant forces by adding vectors• Understand and use Newton's second law, $F=ma$• Apply Newton's second law to vector forces and acceleration• Understand and use Newton's third law• Solve problems involving connected particles	<ul style="list-style-type: none">• Force diagrams• Resultant forces• Newton's first law, second law, third law• Acceleration• Connected particles



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HALF TERM 6	Variable acceleration	<ul style="list-style-type: none">• Understand that displacement,• Use differentiation to solve kinematics problems• Use calculus to solve problems involving maxima and minima• Use integration to solve kinematics problems• Use calculus to derive constant acceleration formula	<ul style="list-style-type: none">• Displacement, velocity and acceleration may be given as functions of time• Calculus (differentiation and integration) to solve problems (kinematics, max/min, constant acceleration formula)